Centralized and Distributed Job Scheduling System Simulation at Exascale

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Outline

- Introduction
- Simulated Architecture
- Technical Consideration
- Centralized Simulator
- Distributed Simulator
- Conclusion and Future Work

Introduction

- MTC
- Job Scheduling Systems
- State-of-art Job Scheduling Systems and Simulators(Centralized/Small scale)
- Exascale

Our Work

- Study scalability and feasibility of JOB SCHEDULING at EXASCALES
- Simulation
	- memory and processing limitations
	- realistic representation of real systems
- Explore central and decentralized systems
- Carry experiments to draw useful conclusions

Simulated Architecture

Technical Consideration

- Hardware, simulating demands great resources
	- Fusion, 48 cores, 64 GB memory
	- Thread limitation! 1:1 mapping discarded
- Software
	- Simulation model, discrete or continuous-events
	- Existing simulation environments
		- GridSim, SimJava, JiST

JiST

- Java in Simulation Time
- Incredibly light for a simulation environment
	- naive ring of million nodes just 1.3 GB
- Easy discrete-event abstraction
- Centralized simulator developed
- Work discontinued
	- Own semantics, debugging
	- Undetermined execution order of events at the same time
	- Weird errors, JiST not support anymore

Centralized Simulator

- Components
- **Client**
- **Server**
- **Nodes**
- **Event Queue**
- Load information Hash Map
- How the simulator works?

• 1. Global Variables

- 2. Job Waiting Queue in the Centralized Server
- Data Structures and the time efficiency

- 3. Event Queue
- (1) Stores events that will happen in future
- (2) Each event has an attribute of occurrence time
- (3) The first event in the event queue is the one that has smallest occurrence time

- 3. Event Queue
- Event type and description

3. Event Queue

- Update frequently. All operations need to maintain the event queue
- Heapsort: takes Θ (Ign) time for removing and inserting and $\Theta(1)$ time for getting the first element
- In java, TreeSet is a set whose elements are ordered using their natural ordering, or by a comparator provided at set creation time. Implemented based on Red-Black tree, guaranteeing Θ (Ign) time for removing and inserting and $\Theta(1)$ time for getting the first.

•4. Load Information

 (1) load = number of busy cores, the range of load is [0, numCoresPerNode]

(2) Using Hash Map to store load information <Key, Value>, Key = load, Value is a hashset containing the node ids which have the load. Update the hashmap takes $\Theta(1)$ time

- 5. Logs and Plot Generation
- Two logs
- task_execute_log: records information such as the 'submission time', 'wait time', 'executing time' for every job. Has switch to turn it on/off.
- summary log: contains information such as 'number of all cores', 'number of executing cores', 'waiting queue length', 'through put'. Implement it with an event instead of separate thread.
- Six ways to write to a log: 'FileOutputStream', 'BufferedOutputStream', 'PrintStream', 'FileWriter', 'BufferedWriter', 'PrintWriter'. 'BufferedWriter' is the fastest one.
- Use ploticus to generate plots

Results and Discussions

• 1. Values of global variables for experiments

Results and Discussions

- 2. Correction Validation
- communication overhead is 0, procTimePerJob = 0 , networkLatency = 0, jobSize = 0. totalNumJobs is 10 times of the total number of cores. Two groups of experiments.
- (1) all the jobs have the same length, 1000 seconds. Simulation time is: 1000 * 10 = 10000
- (2) the average length of all jobs is 500 seconds. Simulation time is around 500 * 10 = 5000
- These two results are exactly what we expect.

Performance Results

Plots

Performance of 1 node, average job length is 5000 seconds, multiply the throughput by 10000

performance of 8192 node, average job length is 5000 seconds, multiply the throughput by 80000, the wait queue length by 1000

Plots

performance of 1048576 node, average job length is 5000 seconds, multiply the number of executed cores by 100, the throughput by 2000000 and the wait queue length by 200000

Distributed Simulator

- Improve the throughput and reliability
- Load balancing is trivial for centralized simulator
- Implement work stealing to achieve load balancing

Work Stealing

- An efficient method to achieve load balancing
- Processes have load imbalance at first. Many benchmarks to generate load imbalance, such as BPC(Bouncing Producer-Consumer), UTS(Unbalanced Tree Search)
- The idle processes poll the busy ones to get work to do.
- Thief: The process that initiates the steal
- Victim: the process that is targeted by the steal

Work Stealing

- Parameters affecting the performance of work stealing
- Can a node steal jobs from all others or just some neighbors?
- How to define neighbors?
- How to select which neighbor to steal jobs
- How many jobs to steal from a selected node?

Changes from the Centralized Simulator

- (1) Remove the centralized server and enhance the functionality of a node.
- (2) A node has a few number of neighbors from which it could steal or dispatch jobs. consider just homogeneous network, that is the distances between a node and its neighbors are the same.
- (3) Keep the global event queue except more events
- (4) Handle jobs straightforwardly, no job entity.
- (5) Client just submits to the first node.
- (6) load = jobListSize numIdleCores
- (7) Do visualization for the load for every node
- (8) Termination condition: all jobs submitted by client are finished

Distributed Simulator Implementation

1. Global Variables for work stealing and visualization

2. Global Event Queue

- Each event now has a global id number
- Types of descriptions of events

3. Visualization

- Efficiently represent load flow in the system
- Simple canvas, each node mapped to a tile
	- color represent load
	- Best results in HSB color space
		- Hue = $(1$ -rate $)$ *0.36
		- Brightness = 1.0
		- Saturation = $1.0-(0.4*(1\text{-rate}))$

1024 nodes, 8 cores, 64 neighbors, 100000000 jobs

1024 nodes, 8 cores, 128 neighbors, 100000000 jobs

1024 nodes, 8 cores, 256 neighbors, 100000000 jobs

Results and Discussions

- 1. Correction Validation
- Run small experiments to trace the procedure of work stealing
- For large experiments, we see that the load balancing is good: the coefficient variance is close to zero

2. Optimal Parameters of Work Stealing

- Amount of jobs to steal
- average job length = 0.5 seconds, pollInterval = 0.05 seconds, numCoresPerNode = 8, totalNumJobs = 10000000, numNeighbors = 2

 Change of throughput with respect to the number Change of coefficient variance with respect to Of nodes for different steal policy and the number of nodes for different steal policy

No. of Neighbors a node has

• average job length = 0.5 seconds, pollInterval = 0.05 seconds, numCoresPerNode = 8, totalNumJobs = 10000000, steal-half policy

Change of throughput with respect to number of nodes for different number of neighbors

Change of coefficient variance with respect to number of nodes for different number of neighbors

No. of Neighbors a node has

4.8

 4.2

extra 3.6
 S 3.6
 S 2.4
 S 1.8
 S 1.2

 0.6

 Ω

• A quarter neighbors is too much in reality

Change of throughput with respect to number of nodes for different number of neighbors

Change of coefficient variance with respect to number of nodes for different number of neighbors

I Gag

No. of Nodes

Neighbor-sart

Neighbor-10^{*} sart

-Neighbor-quarter

Poll Interval

- A node steals jobs from its neighbors, but all of which have no jobs. The node waits for some time and then tries to steal jobs again.
- Intuitively, the longer the average job length is, the larger the interval should be.
- numCoresPerNode = 8, totalNumJobs = 100000000, numNeighbors = a quarter of number of all nodes and steal-half policy.
- Results of changing the poll interval

Number of Cores a node has

- A node could have thousands of cores in the future
- are average job length = 5000 seconds, totalNumJobs = 100000000, numNeighbors = a quarter of number of all nodes, poll interval = 100 seconds and steal-half policy.
- Results of changing the number of cores of a node

Performance Reulsts

- average job length of 5000 seconds and use the optimal combination of parameters, that is stealhalf policy, number of neighbors is a quarter of number of all nodes, poll interval is 100 seconds.
- Group one: 10 billion jobs and each node has 8 cores and we double the number of nodes every time
- Group two: each node has 1000 cores and we double the number of nodes every time and set the number of jobs 10 times of the number of all cores.

Results of Group One

Results of Group Two

Comparison Between two simulators

- The scalability of the centralized one is not as good as the distributed one. The centralized server is a bottleneck. The upper bound of throughput is around 1000. The program runs very fast, it takes about 20 hours to run exascale experiments.
- The distributed simulator scales very well, the increase of throughput is linear with that of number of nodes. As there are so many events in the system, it takes longer to run experiments at the same scale as the centralized one

Conclusion and Future work

- Both the simulators could run experiments at exascale, though it takes longer for the distributed simulator.
- The distributed simulator beats the centralized one in terms of scalability and reliability
- Future work involves memory issues and playing with parameters, such as poll interval, to reduce the real time for distributed simulator. Maybe a fully distributed simulator is our next goal.